

## COURSE SYLLABUS

Academic Year: 2020/2021

Identification and characteristics of the course			
Code	501067-503021	ECTS Credits	6
Course title (English)	Introduction to Automation		
Course title (Spanish)	Introducción a la Automática		
Degree programs	Degree in Electrical Engineering Degree in Electronics and Automatic Engineering Degree in Mechanical Engineering Degree in Materials Engineering Degree in Industrial Technology		
Faculty/School	Industrial Engineering School		
Semester	4th	Course type (compulsory/optional)	Compulsory
Module	Common to the Industrial Field		
Subject matter	Automation and Control		
Lecturer/s			
Name	Room	E-mail	Web page
Jesús Lozano Rogado	D1.14	jesuslozano@unex.es	eii.unex.es
Pilar Merchán García	D1.10	pmerchan@unex.es	eii.unex.es
Subject Area	Systems Engineering and Automation		
Department	Electrical, Electronics Engineering and Automation		
Coordinator (Only if there is more than one lecturer)	Pilar Merchán García		

Competencies *											
Basic Competences	Check With an "X"	General Competences	Check With an "X"	Transversal Competences	Check With an "X"	Specific Competences Basic Formation	Check With an "X"	Specific Competences Common to the Industrial Branch	Check With an "X"	Specific Competences Specific Technology	Check With an "X"
CB1	X	CG1	X	CT1	X	CEFB1		CECRI1		CETE1	
CB2	X	CG2		CT2	X	CEFB2		CECRI2		CETE2	
CB3	X	CG3	X	CT3	X	CEFB3		CECRI3		CETE3	
CB4	X	CG4	X	CT4	X	CEFB4		CECRI4		CETE4	
CB5	X	CG5	X	CT5	X	CEFB5		CECRI5		CETE5	
		CG6	X	CT6	X	CEFB6		CECRI6	X	CETE6	
		CG7	X	CT7	X			CECRI7		CETE7	
		CG8		CT8	X			CECRI8		CETE8	
		CG9		CT9	X			CECRI9		CETE9	
		CG10		CT10	X			CECRI10		CETE10	
		CG11	X					CECRI11		CETE11	
		CG12						CECRI12		CETFG	

\* The sections concerning competencies, course outline, teaching activities, teaching methodology, learning outcomes and assessment methods must conform to those included in the ANECA verified document of the degree program.

Contents
<b>Course outline*</b>
Introduction to the Theory of Systems, Systems and Models, Feedback structures, Dynamic Systems, Automatism and Control Methods
<b>Course contents</b>
<b>BLOCK 1: FUNDAMENTALS OF AUTOMATION</b>
<p>Name of lesson 1: <b>Fundamentals of Automation.</b>            Contents of lesson 1:            Theory (1 hour):                Introduction to automatic systems.                Process control and regulation systems.                Sequential or logical process control systems.                Examples.</p>
<b>BLOCK 2: INDUSTRIAL AUTOMATION.</b>
<p>Name of lesson 2: <b>Introduction to industrial automation.</b>            Contents of lesson 2:            Theory and problems (3 hours):                Introduction.                    Industrial automation systems.                    Programmable logic versus wired logic. Programmable logic controllers: Basic structure.                    Industrial automation elements: sensors, actuators, etc.            Description of the practical activities of lesson 2:  <i>Introduction to the SIEMENS LOGO PLC (2 hours)</i></p> <p>Name of lesson 3: <b>Analysis and synthesis of logical automatism.</b>            Contents of lesson 3:            Theory and problems (4 hours):                Introduction                Combinational and sequential automatism.                    Implementation of combinational automatism. Contact diagrams.            Description of the practical activities of lesson 3:  <i>Automatism implementation in SIEMENS LOGO PLC (I) (2 hours)</i></p> <p>Name of lesson 4: <b>Synthesis of sequential automatism.</b>            Contents of lesson 4:            Theory and problems (6 hours):                Introduction to GRAFCET.                Basic elements.                Logical structures.                Rules of evolution and marking.                Implementation of sequential automatism through GRAFCET.            Description of the practical activities of lesson 4:  <i>Automatism implementation in SIEMENS LOGO PLC (II) (2 hours)</i>  <i>Automatism implementation in SIEMENS LOGO PLC (III) (2 hours)</i></p>

### BLOCK 3: AUTOMATIC CONTROL

Name of lesson 5: **Introduction to feedback control systems.**

Contents of lesson 5:

Theory and problems (2 hours):

Introduction.

Feedback Control.

Name of lesson 6: **Modelling and behaviour of dynamic systems**

Contents of lesson 6:

Theory and problems (10 hours):

Introduction.

Modelling methodology.

Block diagrams.

Transfer function.

Dynamic behaviour:

- a. Transient response analysis.
- b. Analysis of the steady state error.
- c. Stability.

Description of the practical activities of lesson 6:

*Modelling and simulation of dynamic systems (2 hours)*

Name of lesson 7: **Analysis in the frequency domain.**

Contents of lesson 7:

Theory and problems (10 hours):

Introduction.

Frequency Response Function.

Stability analysis using frequency response techniques.

Description of the practical activities of lesson 7:

*Analysis of systems in time and frequency domain (2 hours)*

Name of lesson 8: **Basic control actions.**

Contents of lesson 8:

Theory and problems (4 hours):

Introduction

Steps to Regulator Design

All-nothing controllers

PID controllers

Description of the practical activities of lesson 8:

*Tuning of PID controllers (2 hours)*

#### Educational activities \*

Student workload (hours per lesson)		Lectures	Practical sessions				Monitoring activity	Homework
Lesson	Total	L	HI	LAB	COM	SEM	SGT	PS
1	4	2						2
2	9	3		2				4
3	17.5	4		2			1.5	10
4	21	5		4				12
mid-term exam	7	2						5
5	6	2						4

6	27	10		2			15
7	29.5	10		2		1.5	16
8	13	4		2			7
<b>Assessment **</b>	16	3		1			12
<b>TOTAL ECTS</b>	<b>150</b>	<b>45</b>		<b>15</b>		<b>3</b>	<b>87</b>

L: Lectures (100 students)

HI: Hospital internships (7 students)

LAB: Lab sessions or field practice (15 students)

COM: Computer room or language laboratory practice (30 students)

SEM: Problem-solving classes, seminars or case studies (40 students)

SGT: Scheduled group tutorials (educational monitoring, ECTS type tutorials)

PS: Personal study, individual or group work and reading of bibliography

### Teaching Methodology\*

Among the teaching methodologies included in the formative program, in this course the following are used:

Teaching methodology	Check with an "X" the ones used
1. Explanation and discussion of contents	X
2. Solution, analysis and discussion of examples and exercises	X
3. Oral presentation of assignments	
4. Development of practical cases in labs, computer rooms, seminars, etc.	X
5. Attention to the student and advice of the assignments in small groups	X
6. Search of information prior to the explanation of the contents of an unit or search of complementary information once the activities of a unit have been developed	X
7. Elaboration of assignments either individually or in groups	X
8. Study of each unit: study of contents, preparation of exercises or cases, preparation of the final exam, etc.	X

### Learning outcomes \*

Students will gain knowledge about the basic concepts of automation and basic control methods, as well as for solving real problems and basic automation projects.

### Assessment methods \*

#### **Assessment criteria**

CE1: To understand, recognize and manage the main concepts of the subject: feedback, systems, control actions, automatisms, etc., clearly and rigorously exposing the acquired knowledge (related to: CB1, CB2, CB4, CB5, CG1, CG5-CG7, CG11, CT1 and CECRI6).

CE2: To be able to raise and solve problems on control and automation systems (related to: CB2, CG4, CT2, CT6 and CECRI6).

CE3: To use properly some applications of computer science and TIC's in the automation (related to: CT4, CT5, CT6 and CECRI6).

\*\* Insert as many rows as necessary. For instance, you can include one row for a partial exam and another for the final exam.

CE4: To analyze the results of the practical activities critically and rigorously (related to: CB2, CB3, CG4, CG5, CG6, CG7, CT2, CT3, CT5, CT6 and CT10).

CE5: To demonstrate knowledge of automation and control equipment and systems (related to: CB2, CG5 and CECRI6).

CE6: To demonstrate ability to plan and distribute teamwork. Actively participate in group activities, demonstrating ability to cooperate with the rest of the members of the group and leadership capacity in the activities he/she coordinates (related to: CB2, CB4, CB5, CG1, CG4, CG6, CG11, CT2, CT3, CT5, CT8, CT9 and CT10).

CE7: To be able to present the results of a work, design or project (related to: CB3, CB4, CG1, CT3, CT4, CT5, CT7, CT9 and CECRI6)

### **Assessment activities**

Among the assessment activities included in the formative program, in this course the following are used:

	<b>Range fixed</b>	<b>Ordinary call</b>	<b>Extraordinary call</b>	<b>Global assessment (*)</b>
1. Final exam and/or partial examinations.	0%–80%	60%	60%	75 %
2. Practical activities in: classroom, lab, computers room, visits, etc.	0%–50%	25 %	25 %	25 %
3. Solution and submission of activities (cases, exercises, assignments, projects, etc.), individually and/or in groups.	0%–50%	15%	15%	
4. Active participation in the learning activities.	0%–10%			---
5. Attendance to the learning activities.	0%–10%			---

### **Description of the assessment activities**

#### *Assessment Activity 1:*

- A **mid-term exam** of Block 1 and 2 will be made. Its grade will be 40% of the final exam grade. Students who pass this exam (grading 5 or more), will only be tested of Block 3, in both the ordinary and the extraordinary calls. This grade will be 40% of the final exam grade. Those students who do not pass it will have to attend the final exam and be tested of the whole subject.
- The **final exam** will have two parts: one for Blocks 1 and 2 (part 1) and one for Block 3 (part 2). The grade for part 2 will be 60% of the final exam grade. The students will be tested of the parts that have not passed previously.

#### *Assessment Activity 2:*

- The evaluation of the practices will be based on the reports submitted by the students after each session. It is necessary to pass the practices in order to pass the course. To pass the practices, it is necessary to attend all the sessions and to have favorable reports. Those students who do not attend all the sessions may take a final exam for the internship, both in the ordinary and extraordinary sessions.

*Assessment Activity 3:*

- In addition to the above, various tasks proposed in class or on the virtual campus will be carried out by students at home throughout the course. Their grade will be 15% of the final mark. This evaluation activity is not recoverable.

**Remarks:**

1. Any test will be scored on 10 and the indicated weighting will be applied later.
2. A minimum knowledge of each part is required to pass the subject. This means 5 out of 10 in each of the GG exams.

The global assessment will be held the same day scheduled for the final exam of each call. It will consist of the following parts:

- Written exam consisting of two parts, one corresponding to blocks 1 and 2 and the other to block 3. In the extraordinary call, the students will only have to sit those that do not have been passed previously. The grade of this exam will represent 75% of the final mark.
- Practical activities exam. The grade of this exam will be 25% of the final grade.

**Bibliography (basic and complementary)**

**Basic bibliography**

**BLOCKS 1 & 2**

- Miguel López Ramírez, "Iniciación a la automatización mediante ejercicios prácticos". Marcombo, 2017. ISBN:978-84-267-2433-5.
- Juan Martínez Cabeza de Vaca Alajarín y Luis-Manuel Tomás Balibrea, "Problemas resueltos con autómatas programables mediante GRAGCET". Universidad de Murcia, 1999. ISBN:4-8371-007-2.
- J. Balcells J. L. Romeral, "Autómatas Programables". Marcombo, 1997. ISBN:84-267-1089-1.
- Sergio Ortiz Sousol, José manuel Espinosa Malea, "Sistemas secuenciales programables". Marcombo, 2014. ISBN:978-84-267-2014-4.

**BLOCKS 2 & 3**

- K. Ogata, "Ingeniería de Control Moderna". Prentice Hall, 2010. ISBN: 978-84-8322-660-5. (disponible como recurso electrónico en el catálogo de la biblioteca de la UEX).
- Norman S. Nise, "Control System Engineering". John Wiley & Sons, 2011. ISBN: 978-0470-54756-4.
- Robert N. Bateson, "Introduction to Control System Technology". Prentice Hall, 2001. ISBN: 978-01-3030-688-3.

**Complementary bibliography**

**BLOCK 2**

- García Moreno, E., "Automatización de Procesos Industriales". Serv. Pub. de la UPV, 1999. ISBN:
- Mandado Pérez, Enrique; Marcos Acevedo, Jorge; Fernández Silva, Celso; Armesto Quiroga, José I., "Autómatas Programables y Sistemas Automatizados". Marcombo, 2009. ISBN: 978-84267-1575-3.
- E. Mandado, "Autómatas Programables – Entorno y aplicaciones" Thomson. 2005.

### BLOCK 3

- Benjamin C. Kuo, "Sistemas de Control Automático". Prentice Hall, 1996. ISBN: 978-96-8880-723-1.
- Karl Johan °Aström, Richard M. Murray, "Feedback Systems. An Intro-duction for Scientists and Engineers". Princeton University Press, 2011. ISBN: 978-0-691-13576-2.
- Jairath A.K., "Problems and Solutions of Control Systems: With Essential Theory". CBS Publishing, 2015. ISBN: 978-81-2392-572-1.
- Anastasia Veloni, Alex Palamides, "Control System Problems: Formulas, Solutions, and Simulation Tools". CRC Press, 2011. ISBN: 978-14-3986-850-8.
- Richard C. Dorf and Robert H. Bishop, "Modern Control Systems". Pren-tice Hall, 2011. ISBN: 978-0-13-602458-3.

### Other resources and complementary materials

- J. M. González de Durana "Automatización de Procesos Industriales". Disponible en:  
<http://www.vc.ehu.es/campus/centros/peritos/deptos-p/depsi/jg/API.pdf>
- <https://es.mathworks.com/> Página web de MathWorks.
- The MathWorks, Inc. "Simulink® User's Guide". 2017. Available online en [https://www.mathworks.com/help/pdf\\_doc/Simulink/sl\\_using.pdf](https://www.mathworks.com/help/pdf_doc/Simulink/sl_using.pdf)